Two-Degree-of-Freedom PID **Temperature Controllers**

TN Series

INSTRUCTION MANUAL

TCD210227AE

Autonics

Thank you for choosing our Autonics product.

Read and understand the instruction manual and manual thoroughly before using the product.

For your safety, read and follow the below safety considerations before using. For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

Keep this instruction manual in a place where you can find easily.

The specifications, dimensions, etc are subject to change without notice for product improvement Some models may be discontinued without notice.

Follow Autonics website for the latest information.

Safety Considerations

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- A symbol indicates caution due to special circumstances in which hazards may occur.

★ Warning Failure to follow instructions may result in serious injury or death

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss.(e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.) Failure to follow this instruction may result in personal injury, economic loss or fire.
- 02. Do not use the unit in the place where flammable/explosive/corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.

Failure to follow this instruction may result in explosion or fire.

03. Install on a device panel to use.

Failure to follow this instruction may result in electric shock.

04. Do not connect, repair, or inspect the unit while connected to a power

Failure to follow this instruction may result in fire or electric shock.

05. Check 'Connections' before wiring.

Failure to follow this instruction may result in fire.

06. Do not disassemble or modify the unit.

Failure to follow this instruction may result in fire or electric shock.

⚠ Caution Failure to follow instructions may result in injury or product damage

01. When connecting the power input and relay output, use AWG 20 (0.50 mm²) cable or over, and tighten the terminal screw with a tightening torque of $0.74\,$ to 0.90 N m.

When connecting the sensor input and communication cable without dedicated cable, use AWG 28 to 16 cable and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N m.

Failure to follow this instruction may result in fire or malfunction due to contact

02. Use the unit within the rated specifications.

Failure to follow this instruction may result in fire or product damage

- 03. Use a dry cloth to clean the unit, and do not use water or organic solvent. Failure to follow this instruction may result in fire or electric shock
- 04. Keep the product away from metal chip, dust, and wire residue which flow into the unit.

Failure to follow this instruction may result in fire or product damage.

Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected
- Check the polarity of the terminals before wiring the temperature sensor. For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length. For thermocouple (TC) temperature sensor, use the designated compensation wire for extending wire.
- Keep away from high voltage lines or power lines to prevent inductive noise. In case installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line. Do not use near the equipment which generates strong magnetic force or high frequency noise.
- \bullet Do not apply excessive power when connecting or disconnecting the connectors of the product.

- Install a power switch or circuit breaker in the easily accessible place for supplying or disconnecting the power.
- Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller.
- When changing the input sensor, turn off the power first before changing. After changing the input sensor, modify the value of the corresponding parameter.
- Do not overlapping communication line and power line. Use twisted pair wire for communication line and connect ferrite bead at each end of line to reduce the effect of external noise.
- Make a required space around the unit for radiation of heat. For accurate temperature measurement, warm up the unit over 20 min after turning on the power.
- Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- Do not wire to terminals which are not used.
- This unit may be used in the following environments.
- Indoors (in the environment condition rated in 'Specifications')
- Altitude Max. 2,000 m
- Pollution degree 2
- Installation category II

Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website.

T N 60 - 64 4 63 63 63 - 63 S - 64	т	N (n -	ีด	4	B	4	A	_	ര	S	_	n	
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Size

S: DIN W 48 \times H 48 mm H: DIN W 48 × H 96 mm

L: DIN W 96 \times H 96 mm

2 Control method

No mark: Fixed control P: Program control

Alarm outputs

2: Alarm 1 / 2 4: Alarm 1/2/3/4 6: Alarm 1/2/3/4/5/6

Control output 1

R: Relav S: SSR drive

C: Current or SSR drive

⑤ Control output 2

R: Relav S: SSR drive

C: Current or SSR drive

Communication

N: None R: RS485

Option input/output

No.	Digital input	CT input	Transmission output
006	0	1	0
800	2	1	0
009	3	1	0
014	3	2	0
026	0	1	1
031	0	2	1
035	6	2	1

Manual

For proper use of the product, refer to the manuals and be sure to follow the safety considerations in the manuals.

Download the manuals from the Autonics website.

Software

Download the installation file and the manuals from the Autonics website.

DAQMaster

DAQMaster is comprehensive device management program. It is available for parameter setting, monitoring.

Product Components

Product

· Instruction manual

Bracket

Sold Separately

- Communication converter: SCM Series
- Current transformer (CT)
- Terminal protection cover
- Front cover

Specifications

Power sup	pply	100 - 240 VAC∼, 50/60 Hz ±10%					
ower con	nsumption	≤ 8 VA					
Display ty	pe	11 segment, LCD type (operating value display part: 7 segment)					
Sampling	period	50 / 100 / 250 ms (parameter)					
nput spec	cification	Refer to 'Input Type and Using Range'					
Option	СТ	• 0.0-50.0 A (primary current measurement range) • CT ratio: 1/1,000 • Measurement accuracy: ±5% F.S. ±1digit					
nput	Digital	• Contact · ON: ≤ 2 kΩ, OFF: ≥ 90 kΩ • Non contact · residual voltage ≤ 1.0 V, leakage current ≤ 0.1 mA • Outflow current: ≈ 0.5 mA per input					
	Relay	250 VAC∼ 3A 1a					
Control	SSR	12 VDC== ±2 V, ≤ 20 mA					
output	Current	DC 0 - 20 mA or DC 4 - 20 mA (parameter), Load resistance: \leq 500 Ω					
	Alarm	250 VAC∼ 3 A 1a					
Option utput Transmission		DC 4 - 20 mA (load resistance: \leq 500 Ω , output accuracy: $\pm 0.3\%$ F.S.)					
	Communication	RS485					
	Туре	ON/OFF, P, PI, PD, PID					
	Multi SV	≤ 4 SV					
Control	Group PID	≤ 8 group					
ype	Zone PID	4 zones					
	ARW (Anti Reset Windup)	50 to 200 %					
	Program	≤ 10 patterns					
rogram ontrol	Step	≤ 200 steps (1 pattern: ≤ 20 steps)					
Setting type		Time setting					
lysteresis	5	• Thermocouple, RTD: 1 to 100 (0.1 to 100.0) °C/°F • Analog: 1 to 100 digit					
roportio	nal band (P)	0.1 to 999.9 °C (0.1 to 999.9%)					
ntegral tii	me (I)	0 to 9,999 sec					
erivative	time (D)	0 to 9,999 sec					
ontrol cy		Relay / SSRP output: 0.1 to 120.0 sec Selectable current or SSR drive output: 1.0 to 120.0 sec					
Ianual re	set	0.0 to 100.0%					
ielectric	strength	Between the charging part and the case: 3,000 VAC ~ 50/60 Hz for 1 min					
ibration	ı	0.75 mm amplitude at frequency of 5 to 55 Hz (for 1 min) in each XY, Z direction for 2 hours					
elay life	Mechanical	• OUT1/2: ≥ 5,000,000 operations • AL1/2/3/4/5/6: ≥ 20,000,000 operations					
ycle	Electrical	OUT1/2: ≥ 200,000 operations AL1/2/3/4/5/6: ≥ 100,000 operations					
nsulation	resistance	≥ 100 MΩ (500 VDC== megger)					
nsulation	type	Double insulation or reinforced insulation (mark: , dielectric strength between the measuring input part and the power part: 3 kV)					
loise imm	nunity	$\pm 2\text{kV}$ square shaped noise by noise simulator (pulse width: $1\mu\text{s}$ R-phase, S-phase					
Memory retention		pprox 10 years (non-volatile semiconductor memory type)					
mbient temperature		-10 to 50 °C, storage: -20 to 60 °C (no freezing or condensation)					
mbient humidity		35 to 85%RH					
rotection structure		IP65 (Front panel, IEC standards)					
oader po	rt	• TNS: top side • TNH, TNL: front side					
		Bracket					
oader port ccessory		•TNS: ≈ 128 g (≈ 156 g) •TNH: ≈ 184 g (≈ 286 g)					
	ht (packaged)	• INS. ≈ 128 g (≈ 156 g) • TNL: ≈ 301 g (≈ 443 g) • E					

Communication Interface

RS485

Comm. protocol	Modbus RTU/ASCII, Sync-Master, PLC ladderless			
Connection type	RS-485, RS-422A			
Application standard	EIA RS485 compliance with			
Maximum connection	32 units (address: 01 to 99)			
Synchronous method	Asynchronous			
Comm. Method	Two-wire half duplex			
Comm. effective range	≤ 800 m			
Comm. speed	≤ 115,200 bps			
Response time	5 to 99 ms (default: 20 ms)			
Start bit	1 bit (fixed)			
Data bit	8 bit (fixed)			
Parity bit	None (default), Odd, Even			
Stop bit	1 bit, 2 bit (default)			
EEPROM life cycle ≈ 1,000,000 operations (Erase / Write)				
1 sharester of MadDua DTU is fixed				

 ¹ character of ModBus RTU is fixed at 11 bit.

Input Type and Using Range

The setting range of some parameters is limited when using the decimal point display.

Input type		point	Display	Using range (°C)	Using range (°F)
	IV (CA)	1	K E R.H	-200 to 1,350	-328 to 2,463
	K (CA)	0.1	K E A.L	-199.9 to 999.9	-199.9 to 999.9
	J (IC)	1	JI E.H	-200 to 800	-328 to 1,472
	J (IC)	0.1	JI C.L	-199.9 to 800.0	-199.9 to 999.9
	E (CR)	1	E C R.H	-200 to 800	-328 to 1,472
	E (CR)	0.1	E C R.L	-199.9 to 800.0	-199.9 to 999.9
	T (CC)	1	E € €.H	-200 to 400	-328 to 752
	1 (CC)	0.1	E C C.L	-199.9 to 400.0	-199.9 to 752.0
	B (PR)	1	ь РР	0 to 1,800	32 to 3,272
Thermo	R (PR)	1	R PR	0 to 1,750	32 to 3,182
-couple	S (PR)	1	5 PR	0 to 1,750	32 to 3,182
-couple	N (NN)	1	N NN	-200 to 1,300	-328 to 2,372
	C (TT) 01)	1	[EE	0 to 2,300	32 to 4,172
	G (TT) 02)	1	G EE	0 to 2,300	32 to 4,172
	L (IC)	1	LI E.H	-200 to 900	-328 to 1,652
		0.1	LI C.L	-199.9 to 900.0	-199.9 to 999.9
	L (RUS)	1	L R.H	-200 to 800	-328 to 1,472
		0.1	L R.L	-199.9 to 800.0	-199.9 to 999.9
	U (CC)	1	U C C.H	-200 to 400	-328 to 752
		0.1	U C C.L	-199.9 to 400.0	-199.9 to 752.0
	Platinel II	1	PLII	0 to 1,390	32 to 2,534
	Cu50 Ω	0.1	CU 5	-199.9 to 200.0	-199.9 to 392.0
	Cu100 Ω	0.1	C U 10	-199.9 to 200.0	-199.9 to 392.0
	JPt100 Ω	1	JPE.H	-200 to 650	-328 to 1,202
RTD	JP(100 12	0.1	JP E.L	-199.9 to 650.0	-199.9 to 999.9
KID	DPt50 Ω	0.1	dPE5	-199.9 to 600.0	-199.9 to 999.9
	DPt100 Ω	1	dPt.H	-200 to 650	-328 to 1,202
	DF1100 12	0.1	dPt.L	-199.9 to 650.0	-199.9 to 999.9
	Nickel120 Ω	1	N1 12	-80 to 200	-112 to 392
	0 to 10 V	-	AV I	0 to	10 V
	0 to 5 V	-	AV2	0 to	5 V
Analog	1 to 5 V	-	AV3	1 to	5 V
Allalog	0 to 100 mV	-	AMY I	0 to	100 mV
	0 to 20 mA	-	AMA I	0 to	20 mA
	4 to 20 mA	-	AMA5	4 to	20 mA
	line resistance per		sor		

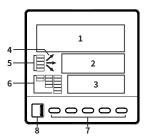
⁰¹⁾ C (TT): Same as existing W5 (TT) type sensor 02) G (TT): Same as existing W (TT) type sensor

■ Display accuracy

Input type	Using temperature	Display accuracy
Thermo -couple RTD	At room temperature (23°C ±5°C)	$ \begin{array}{l} (\text{PV}\pm0.2\% \text{ or }\pm1^{\circ}\text{C higher one)}\pm1\text{-digit} \\ \bullet \text{ Thermocouple K, J, T, N, E below -100^{\circ}\text{C and L, U, PLII,} \\ \text{RTD Cu50}\ \Omega, \text{DPt50}\ \Omega: (\text{PV}\pm0.3\% \text{ or }\pm2^{\circ}\text{C higher one)}\pm1\text{-digit} \\ \bullet \text{Thermocouple C, G and R, S below 200^{\circ}\text{C}:} \\ (\text{PV}\pm0.3\% \text{ or }\pm3^{\circ}\text{C higher one)}\pm1\text{-digit} \\ \bullet \text{Thermocouple B below 400^{\circ}\text{C}:} \text{There is no accuracy standards} \\ \end{array} $
	Out of room temperature range	$ \begin{array}{l} (\text{PV}\pm0.5\% \text{ or } \pm 2^{\circ}\text{C higher one}) \pm 1\text{-digit} \\ \bullet \text{RTD Cu50 } \Omega, \text{DPt50 } \Omega; (\text{PV}\pm0.5\% \text{ or } \pm 3^{\circ}\text{C higher one}) \\ \pm 1\text{-digit} \\ \bullet \text{Thermocouple R, S, B, C, G:} \\ (\text{PV}\pm0.5\% \text{ or } \pm 5^{\circ}\text{C higher one}) \pm 1\text{-digit} \\ \bullet \text{Other sensors:} \leq \pm 5^{\circ}\text{C } (\leq -100^{\circ}\text{C}) \end{array} $
Analog	At room temperature (23°C ±5°C)	\pm 0.2% F.S. \pm 1-digit
	Out of room temperature range	±0.5% F.S. ±1-digit

Unit Descriptions

- Below is based on TNL Series.
- The shape and function of each part may be different depending on the series, and it is possible to check the additional information in the user manual.



1. PV display part (White)

- Setting mode: Displays parameter name
- 2. SV display part (Green)
- 3. Operating value display part (Yellow)
- RUN mode: Displays selected value among MV (Manipulated output value), CT, TIME with unit.
- 4. Temperature control indicator
- based on SV $PV > SV (\nearrow)$, $PV = SV (\rightarrow)$, $PV < SV (\searrow)$
- status of up (\nearrow) , hold (\rightarrow) , down (\searrow) .

5. Operation status indicator

Display	Name	Description				
LOCK	Lock	Turns ON during key lock status.				
PROG	Program	Turns ON during program control.				
WAIT	Wait	Turns ON during waiting status.				
HBA1/2	Heater break alarm	Turns ON when the heater break alarm output is ON.				

6. Output status indicator

Display	Name	Description
OUT1/2	Control output	Turns ON when the control output is ON
AT	Auto tuning	Flashes during auto tuning every 1 sec
MAN	Manual control	Turns ON during manual control mode
STOP	Control output stop	Turns ON during control output stop mode
HOLD	Program control hold	Turns ON when program control is hold status
AL1 to 6	Alarm output	Turns ON when the alarm output is ON

• RUN mode: Displays PV (Present value) and unit.

- RUN mode: Displays SV (Setting value) and unit. · Setting mode: Displays parameter setting value.

- Fixed control: Relative PV value status display
- Program control: Displays temperature control

7. Input key				
Display	Name			
[U]	User key			
[M]	Mode key			
$[\blacktriangleleft], [\blacktriangledown], [\blacktriangle]$	Setting value control key			

8. PC loader port

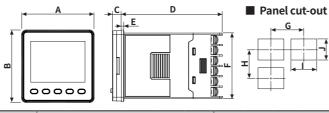
For connecting communication converter (SCM-USP).

Errors

Display	Input	Description	Output	Troubleshooting	
Temperature sensor PEN Analog		Flashes at 0.5 sec interval when input sensor is disconnected or sensor is not connected.	'Sensor error, MV' parameter setting value	Check input sensor status.	
		Flashes at 0.5 sec interval when input is over F.S. $\pm 10\%$.	'Sensor error, MV' parameter setting value	Check analog input status.	
нннн	Temperature sensor	Flashes at 0.5 sec interval if the input value is above the input range.	Heating: 0%, Cooling: 100%	When input is within the rated input representations.	
пппп	Analog	Flashes at 0.5 sec interval if the input value is over 5 to 10% of high limit or low limit value.	Normal output		
LLLL	Temperature sensor	Flashes at 0.5 sec. interval if the input value is below the input range.	Heating: 100%, Cooling: 0%	input range, this display disappears.	
	Flashes at 0.5 sec interval if the input value is over 5 to 10% of low limit or high limit value.		Normal output		
ERR	Flashes at 0.5 sec interval if there is error for setting and it returns to the error-before screen.		-	Check setting method.	

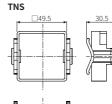
Dimensions

- Unit: mm, For the detailed drawings, follow the Autonics website.
- Below is based on TNS Series.



	Body		Panel cut-out							
	Α	В	С	D	E	F	G	Н	I	J
TNS	49	49	6	69	1.5	44.8	≥ 65	≥ 65	45 ^{+0.6}	45 ^{+0.6}
TNH	49	97	6	69	1.5	91.5	≥ 65	≥ 115	45 ^{+0.6}	92 0 0
TNL	97	97	6	69	1.5	91.5	≥ 115	≥ 115	92+0.8	92+0.8

■ Bracket

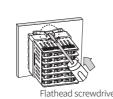


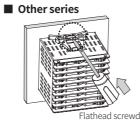




Installation Method

■ TNS

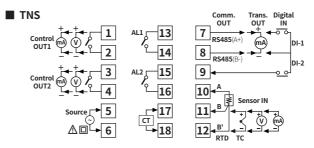




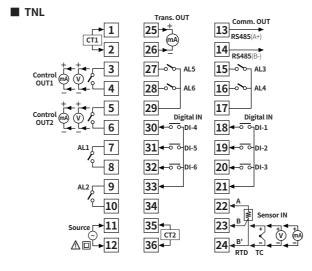
Insert the unit into a panel, fasten the bracket by pushing with tools with a flathead screwdriver.

Connections

 $\bullet \ \mathsf{Digital} \ \mathsf{input} \ \mathsf{is} \ \mathsf{not} \ \mathsf{electrically} \ \mathsf{insulated} \ \mathsf{from} \ \mathsf{internal} \ \mathsf{circuits}, \mathsf{so} \ \mathsf{it} \ \mathsf{should} \ \mathsf{be} \ \mathsf{insulated}$ when connecting other circuits.



I TNH	Comm. OUT
1	13 RS485(A+)
2	14 RS485(B-)
Control (m) (V)	15-0 AL3
OUT1 4 4	16-00- AL4
Control mA V 6	Trans. Digital IN OUT + 18 - O O DI-1
AL1 7	(mA)
% _8	20 ← ○ DI-3
AL2 9	21
′0_10	22 A Sensor IN
Source 11	23 dB delisor in
△□→12	24 RTD TC



Crimp Terminal Specifications

• Unit: mm, Use the crimp terminal of follow shape





Fork crimp terminal

Round crimp terminal

Initial Display When Power is ON

When power is supplied, after all display will flash for 1 sec, model name is displayed sequentially. After input sensor type will flash twice, enter into RUN mode.

Display part	1. Model	2. Model	3. Input specification	4. RUN mode
PV	Ł N 5.P	R5	£ YPE	oPEN
SV	42RR	006	K E R.H	0

Мо	de Setting							
	Auto before			Password	Key input	(ey input Entering mo		
	entering to mode		Password input	Pass	Auto	Selected mode Password input		
	(**************************************	→		Fail	$[\blacktriangleleft], [\blacktriangle], [\blacktriangledown]$			
	password)				[MODE]	Run mod	de	
	[◀], [▲], [▼] (in manual control)	\rightarrow	MV setting	Move digits: $[\blacktriangleleft]$ Change value: $[\blacktriangle], [\blacktriangledown]$				
	[◀], [▲], [▼] (in auto control)	\rightarrow	SV setting	Save: [MOI over 3 sec	DE] or no key i	input →		
	[▼] + [▲] 3 sec	\rightarrow	Control output run/stop	Auto →				
RUN	[M] + [A]	\rightarrow	Operating value display part (MV/CT/TIME) setting	Auto	Auto			
	[U] + [◀] / [▼] / [▲] 2 sec		Shortcut key 1/2/3	Auto		\rightarrow		
	[◀] + [▼] 3 sec	\rightarrow	Key lock	[◄] + [▼] 3	3 sec	\rightarrow		
	[M] 2 sec	\rightarrow	Parameter group	[◀] 2 sec		→		
	[U] 2 sec	\rightarrow	User customized parameter group	[U]	J] →			
	[◀] + [▲] + [▼] 5 sec	\rightarrow	Parameter reset	Auto		\rightarrow		

 $[\]bullet \, \mathsf{TNS} \, \mathsf{series} \, \mathsf{does} \, \mathsf{not} \, \mathsf{support} \, \mathsf{'MV} \, \mathsf{setting'}, \, \mathsf{'Operation} \, \mathsf{value} \, \mathsf{display} \, \mathsf{part} \, \mathsf{setting'} \, \mathsf{mode}. \, \mathsf{For} \, \mathsf{the} \, \mathsf{details}, \mathsf{refer} \, \mathsf{to} \, \mathsf{the} \, \mathsf{details}, \, \mathsf{value} \, \mathsf{display} \, \mathsf{part} \, \mathsf{setting'} \, \mathsf{mode}. \, \mathsf{For} \, \mathsf{the} \, \mathsf{details}, \, \mathsf{refer} \, \mathsf{to} \, \mathsf{the} \, \mathsf{details}, \, \mathsf{th$

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